

LAST TIME:

Given \vec{x} and \vec{v} now



Use Newton's second law to predict rate of change of velocity: $\frac{d\vec{v}}{dt} = \frac{1}{m} \vec{F}$ ← this is 3 equations!

Rate of change of position: $\frac{d\vec{x}}{dt} = \vec{v}$

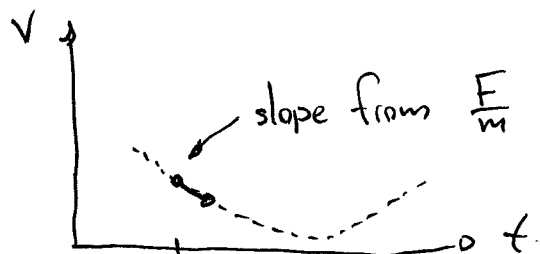
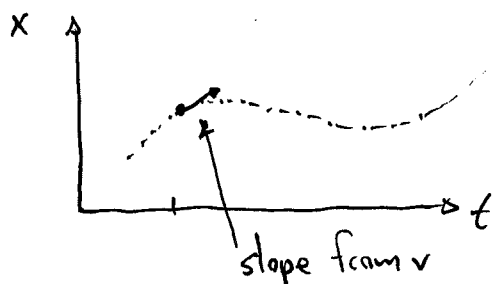


Use these rates of change to predict \vec{x} and \vec{v} at a slightly later time:

$$\vec{v}(t + \delta t) \approx \vec{v}(t) + \delta t \cdot \left(\frac{d\vec{v}}{dt} \right)$$

$$\vec{x}(t + \delta t) \approx \vec{x}(t) + \delta t \cdot \left(\frac{d\vec{x}}{dt} \right)$$

repeat



Follow the arrow a tiny bit to the next point.

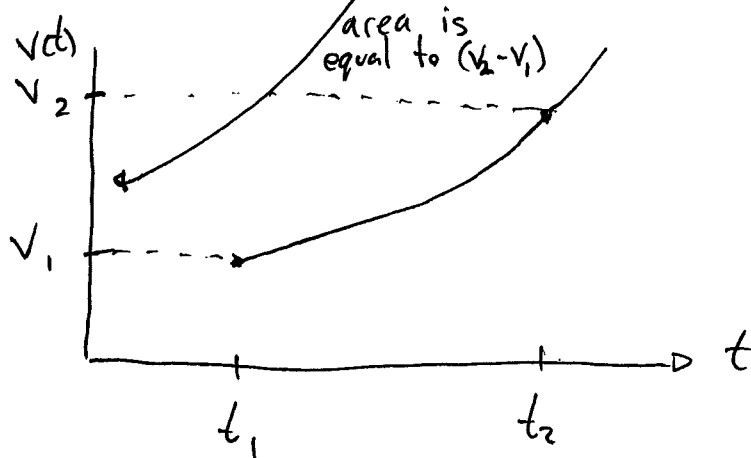
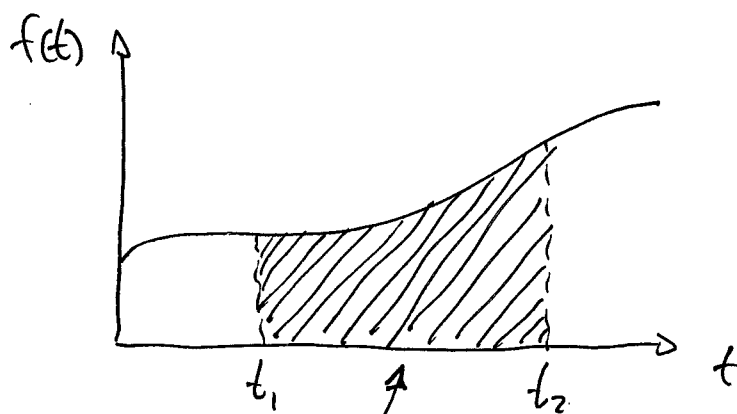
RECAP INTEGRATION:

If $\frac{dv}{dt} = f(t)$ ← this is the acceleration, but we're calling it $f(t)$ so it looks like math.

Then $v(t_2) = v(t_1) + \left\{ \text{area under graph of } f(t) \text{ between } t_1 \text{ and } t_2 \right\}$

$$= v(t_1) + \int_{t_1}^{t_2} f(t) dt$$

↑ this is the definition in words.

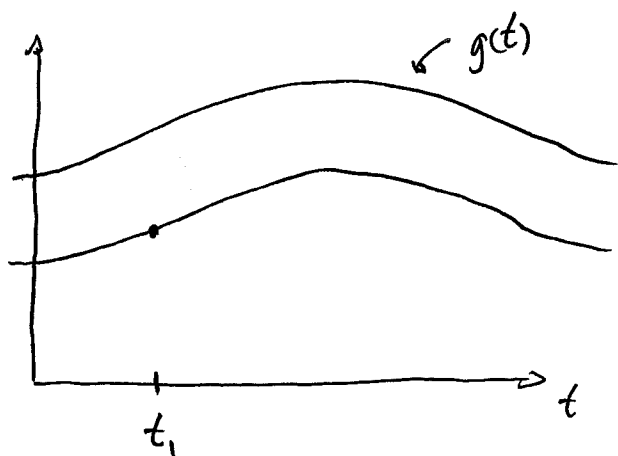


ANOTHER WAY:

Guess a function $g(t)$ such that

$$\frac{dg}{dt} = f.$$

Then $g(t)$ and $v(t)$ have the same time derivative, but differ by a constant.



Given v at some time t we can find the constant.

$$\begin{aligned} \text{So } v(t) &= g(t) + C \\ v(t_1) &= g(t_1) + C \end{aligned} \quad \left. \begin{array}{l} \text{if we know } v(t) \text{ then} \\ C = v(t_1) - g(t_1) \end{array} \right\}$$

And

$$v(t) = v(t_1) + [g(t) - g(t_1)]$$

↑
we're given this

↑
we guess $g(t)$ and evaluate this.

SUMMARY:

$$\frac{dv}{dt} = f \quad \begin{array}{l} \rightarrow v(t_2) = v(t_1) + \int_{t_1}^{t_2} f(t) dt \\ \rightarrow v(t_2) = v(t_1) + [g(t_2) - g(t_1)] \end{array}$$

where g is a function
such that $\frac{dg}{dt} = f$.

It must be true that:

$$\underbrace{\int_{t_1}^{t_2} f(t) dt}_{\text{area under the graph}} = \underbrace{g(t_2) - g(t_1)}_{\text{difference in 2 numbers.}}$$

\rightarrow Part of the "Fundamental Theorem of Calculus."