

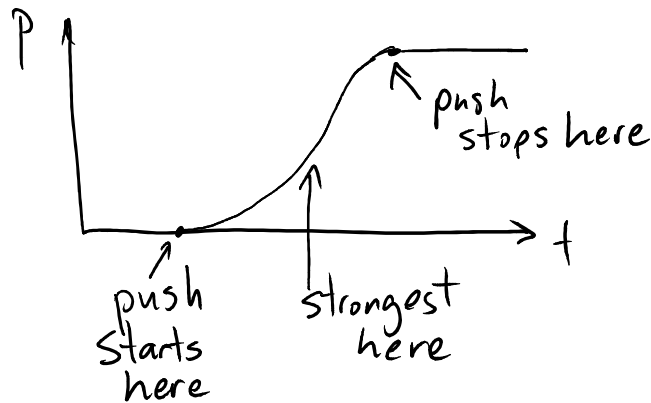
LAST TIME:

Momentum conservation $\xrightarrow{\text{isolated object}}$ Newton's 1st Law

★ two objects that experience the same external influence will experience the same change in momentum



We can quantify the strength of an external influence by the change in momentum it produces:
e.g. pushing an object initially at rest:



Can define FORCE by $\frac{dp}{dt}$ on some test object.

e.g. Force in Newtons = change in momentum per second of 1kg space-salmon

- Now apply this force to any other object for some time dt .
- Change in momentum dp will be SAME as for the test object (by result * above)

So:

$$\frac{d\vec{p}}{dt} = \vec{F}_{NET}$$

for ANY object

← This is NEWTON'S 2ND LAW

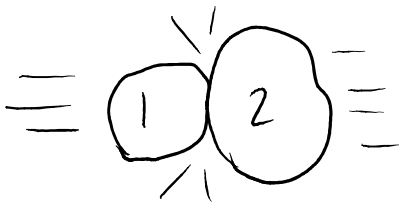
Small speeds: $\vec{p} = m\vec{v}$

$v \ll c$

speed
of light

$$\text{so } \vec{F} = \frac{d\vec{p}}{dt} = \frac{d}{dt}(m\vec{v}) = m \frac{d\vec{v}}{dt} = m\vec{a}$$

Also: for interaction between 2 objects,

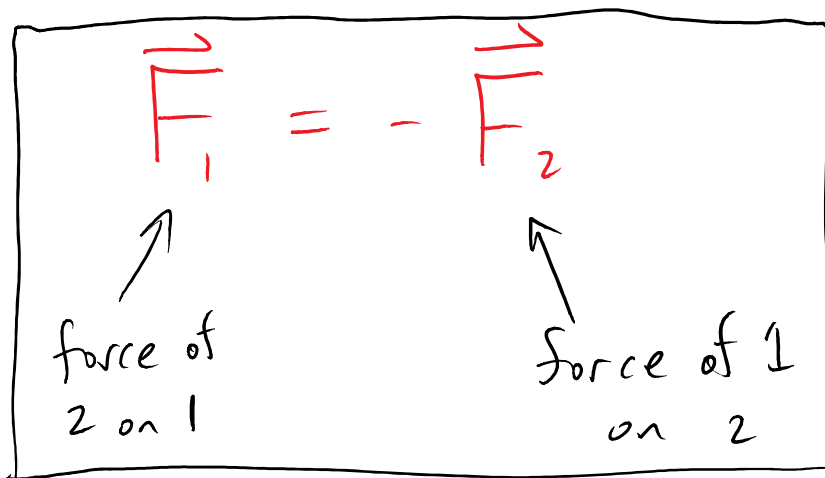


In time Δt , total \vec{p} conserved so

$$\Delta \vec{p}_1 = - \Delta \vec{p}_2$$

$$\Rightarrow \frac{\Delta \vec{p}_1}{\Delta t} = - \frac{\Delta \vec{p}_2}{\Delta t}$$

Conclusion:



Newton's
3rd
Law

NOT always true
of NET force.
on 1 + 2 since
could be other forces.

PREDICTING THE FUTURE

$$\frac{d\vec{v}}{dt} = \frac{1}{m} \vec{F}_{NET}$$

vector sum of forces
on object

depends on position,
velocity, environment
of object

e.g. gravity
friction
push/pull
normal
air drag
;

Assuming we know forces for all possible
positions + velocities of object, can predict
 $\vec{r}(t)$, $\vec{v}(t)$ from $\vec{r}(t=0)$ and $\vec{v}(t=0)$

key point: $\frac{dv}{dt} = \lim_{\Delta t \rightarrow 0} \frac{v(t+\Delta t) - v(t)}{\Delta t} = \frac{1}{m} F_{NET}$

for $\Delta t = \varepsilon$ (ε small)

$$\frac{v(t+\varepsilon) - v(t)}{\varepsilon} \stackrel{\text{approx}}{\approx} \frac{1}{m} F_{NET}$$

$$v(t+\varepsilon) \approx v(t) + \varepsilon \cdot \frac{1}{m} F_{NET}$$

velocity at slightly later time velocity now depends on position & velocity now

Also: $x(t+\varepsilon) \approx x(t) + \varepsilon \cdot v(t)$ since $\frac{dx}{dt} = v$

Given x, v now, get x, v at a slightly later time. Repeat!

More & more precise as $\varepsilon \rightarrow 0$.