

Today's Plan:

Announcements

Review Activity 1 and 2

Programming in C continue

Activity 3

Using ADC

Announcements

- Lecture test next week during the lecture 20 minutes. Understand the I/O port commands and what each parameter means. Understand setting up of the interrupt.
- Collaborative Ultra
- Adjustable voltage on the power supply: Do not use it!
- Power supply connector.
- Activities 1 and 2 were due before the lecture. No late submissions – I will give you answers now
- Late report submissions 10% a day.

Activity 1

- Write commands which will configure all pins of port 1 as inputs, and move the value from port 1 to register R7. Write the binary number which will be in the 16 bit register R7 after these operations assuming that the pins of port 1 were connected to 3V.

```
mov.b 0x00, &P1DIR
```

```
mov.b &P1IN, R7
```

```
R7 : 0x00FF
```

```
0000000011111111b
```

← *mov.b used so as to write to only P1DIR and not to P1DIR and whatever is next in memory (P1IFG).*

← *mov.b used to copy only P1IN, and not also whatever is next in memory (P2OUT).*

Activity 2

What are the values of R7 and the Z, N, and C bits after the following commands (assuming they were all 0 initially)

Z = 0 N = 0 C = 0 R7 = 0

mov.w #0xF0F0, R7 Z = ? N = ? C = ? R7 = ?

add.w #0xF000, R7 Z = ? N = ? C = ? R7 = ?

sub.w #0xE0F0, R7 Z = ? N = ? C = ? R7 = ?

Activity 2

What are the values of R7 and the Z, N, and C bits after the following commands (assuming they were all 0 initially)

	Z = 0	N = 0	C = 0	R7 = 0
mov.w #0xF0F0, R7	Z = 0	N = 0	C = 0	R7 = 0xF0F0
add.w #0xF000, R7	Z = ?	N = ?	C = ?	R7 = ?
sub.w #0xE0F0, R7	Z = ?	N = ?	C = ?	R7 = ?

mov doesn't touch the status bits

Activity 2

What are the values of R7 and the Z, N, and C bits after the following commands (assuming they were all 0 initially)

	Z = 0	N = 0	C = 0	R7 =
mov.w #0xF0F0, R7	Z = 0	N = 0	C = 0	R7 = 0xF0F0
add.w #0xF000, R7	Z = 0	N = 1	C = 1	R7 = 0xE0F0
sub.w #0xE0F0, R7	Z = ?	N = ?	C = ?	R7 = ?

0xE0F0 is negative (if interpreted as signed)

Activity 2

What are the values of R7 and the Z, N, and C bits after the following commands (assuming they were all 0 initially)

		Z = 0	N = 0	C = 0	R7 =
mov.w #0xF0F0, R7	Z = 0	N = 0	C = 0	R7 = 0xF0F0	
add.w #0xF000, R7	Z = 0	N = 1	C = 1	R7 = 0xE0F0	
sub.w #0xE0F0, R7	Z = 1	N = 0	C = 1	R7 = 0x0000	

The carry bit is set because of the way the subtraction is done. Subtraction is done by adding the inverse of the first operand, plus one. The carry bit is set if there is a carry from the addition.

Programming in C

```
#include <msp430.h>
```

```
volatile unsigned int i=0;
```

```
int main(void)
```

```
{
```

```
    WDTCTL = WDTPW + WDTHOLD;
```

```
    P1DIR |= 0x41;           for( initialization ; condition ; increment expression )
```

```
    for(;;){
```

```
        for ( i = 0 ; i < 20000 ; i++ ){
```

```
            if ( i == 0 )
```

```
                P1OUT ^= 0x01;
```

```
            if ( i == 6000)
```

```
                P1OUT ^= 0x40;
```

```
        }
```

```
    }
```

```
}
```


Programming in C

```
#include <msp430.h>
```

```
volatile unsigned int i=0;
```

```
int main(void)
```

```
{
```

```
    WDTCTL = WDTPW + WDTHOLD;
```

```
    P1DIR |= 0x41;
```

```
    for(;;){
```

```
        for ( i = 0 ; i < 20000 ; i++ ) {
```

```
            if ( i ← == 0 )
```

```
                P1OUT ^= 0x01;
```

```
            if ( i == 6000 )
```

```
                P1OUT ^= 0x40;
```

```
        }
```

```
    }
```

```
}
```

Test if i is 0. Note that equality is tested with ==
A single = is an assignment.

Programming in C

```
#include <msp430.h>
```

```
volatile unsigned int i=0;
```

```
int main(void)
```

```
{
```

```
    WDTCTL = WDTPW + WDTHOLD;
```

```
    P1DIR |= 0x41;
```

This is equivalent to
 $P1OUT = P1OUT | 0x41;$
| is the bitwise or

```
    for(;;){
```

```
        for ( i = 0 ; i < 20000 ; i++ ){
```

```
            if ( i == 0 )
```

```
                P1OUT ^= 0x01;
```

```
            if ( i == 6000)
```

```
                P1OUT ^= 0x40;
```

```
        }
```

```
    }
```

```
}
```

This is equivalent to
 $P1OUT = P1OUT ^ 0x01;$
^ is exclusive or

Programming in C

```
#include <msp430.h>
```

```
volatile unsigned int i=0;
```

```
int main(void)
```

```
{
```

```
    WDTCTL = WDTPW + WDTHOLD;
```

```
    P1DIR |= 0x41;
```

```
    for(;;){
```

```
        for ( i = 0 ; i < 20000 ; i++ ){
```

```
            if ( i == 0 )
```

```
                P1OUT ^= 0x01;
```

```
            if ( i == 6000 )
```

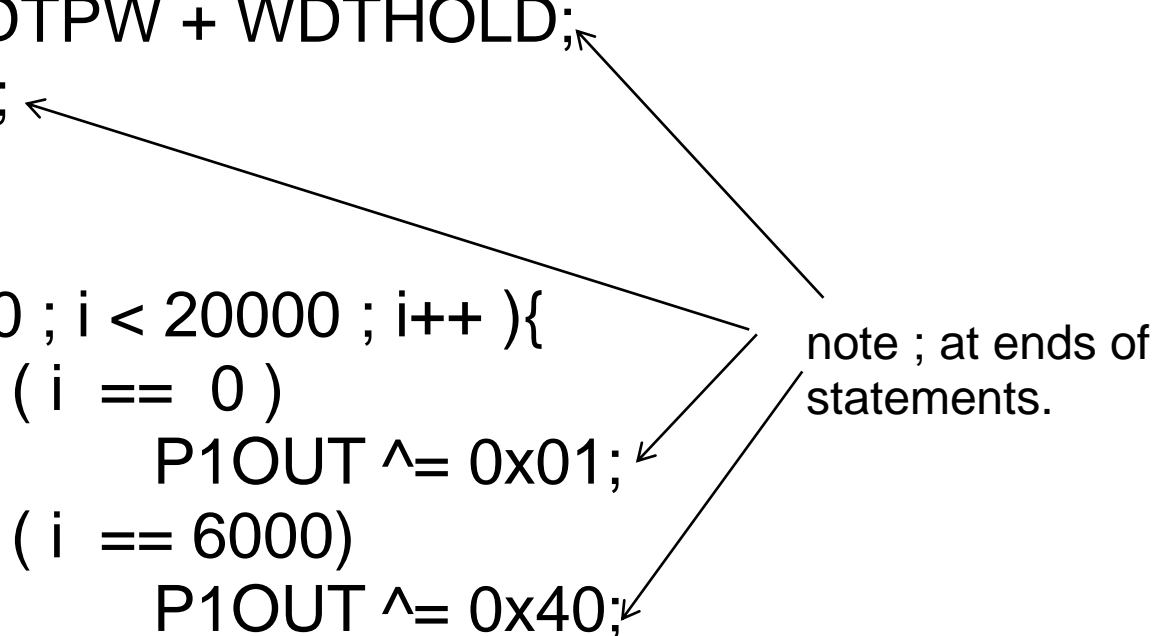
```
                P1OUT ^= 0x40;
```

```
        }
```

```
    }
```

```
}
```

note ; at ends of statements.



```
if ( i == 0 ){  
    a = 2;  
    b = 3;  
}
```

← braces

vs

```
if ( i == 0 )  
    a = 2;  
    b = 3;
```

```
if (i == 0) a = 2;  
b = 3;
```

Never do this:

```
if ( i == 0 );  
a = 2;
```

tabbing is helpful
for readability.
Most useful
editors will help
tabbing

The compiler itself ignores whitespace – it's just for readability

```
if ( i == 0 ){  
    a = 2;  
    b = 3;  
}
```

← braces

vs

```
if ( i == 0 )  
    a = 2;  
    b = 3;
```

executed even if
i != 0 →

Never do this:

```
if ( i == 0 );  
a = 2;
```

```
if (i == 0) a = 2;  
b = 3;
```

tabbing is helpful
for readability.
Many useful
editors will help
tabbing

The compiler itself ignores whitespace – it's just for readability

Bitwise AND, OR and Exclusive OR

p	q	p & q	p q	p ^ q
0	0	0	0	0
0	1	0	1	1
1	1	1	1	0
1	0	0	1	1

Programming in C

Operators:

=, +, -, *, /

% - modulus

& - bitwise AND

| - bitwise OR

^ - bitwise XOR

~ - bitwise NOT

<< - bitshift left

>> - bitshift right

Comparison:

==, <, >, !=

if (i < 3), if (i != 3)

&& - logical AND

if (i == 1 && j == 2)

|| - logical OR

if (i == 1 || j == 2)

! logical NOT

Programming in C

Data types:

char, unsigned char – 8 bit integer

short, unsigned short (usually 16 bit integer, size on msp430 might be 8)

int, unsigned int – usually an integer of the native word size 16 bits

long, unsigned long – 32 bit integer

long long, unsigned long long – 64 bit integer

float – floating point number (32 bits)

(floating point operations are very “expensive” on a processor like the msp430 that lacks a dedicated fpu).

Programming in C



```
#include <msp430.h>
```

```
volatile unsigned int i=0;
```

```
int main(void)
```

```
{
```

```
    WDTCTL = WDTPW + WDTHOLD;
```

```
    P1DIR |= 0x41;
```

```
    for(;;){
```

```
        for ( i = 0 ; i < 20000 ; i++ ){
```

```
            if ( i == 0 )
```

```
                P1OUT ^= 0x01;
```

```
            if ( i == 6000)
```

```
                P1OUT ^= 0x40;
```

```
        }
```

```
    }
```

```
}
```

Programming in C

Libraries:

there are some “standard” libraries available that extend the operations you can easily use.

eg:

the math library gives access to functions like:

$\sin(x)$, $\cos(x)$, $\tan(x)$, \sqrt{x} , $\ln(x)$, $\log(x)$ etc...

To use math functions, you need to:

`#include <math.h>` at the top of the file, and also put:

`-lm` on the compilation command line.

Other libraries provide routines for string manipulations and other things...

These libraries tend to take up a substantial amount of flash and consume (precious) ram. You should try to avoid these on the MSP430 if at all possible!

Programming in C

```
int multiply_together(int x, int y)
{
    return x*y;
}
```

← You can define other functions that can take arguments and return values.

...

```
y = multiply_together(4, 8);
```

...

The function definition either needs to come in the file before you call it, or you need to supply a *function prototype* before you call it.

A prototype for this function would simply be:

```
int multiply_together(int x, int y);
```

Data types:

char, unsigned char – 8 bit integer (-128 to 127 or 0 to 255)

short, unsigned short (usually 16 bit integer, size on msp430 ?)

int, unsigned int – usually an integer of the native word size: 16 bits
(-32768 to 32767 or 0 to 65536)

long, unsigned long – 32 bit integer
($\sim -2 \times 10^9$ to $\sim 2 \times 10^9$ or 0 to $\sim 4 \times 10^9$)

long long, unsigned long long – 64 bit integer
($\sim -9 \times 10^{18}$ to $\sim 9 \times 10^{18}$ or 0 to $\sim 2 \times 10^{19}$)

float – floating point number (32 bits)

(floating point operations are very expensive on a processor like the msp430 that lacks a dedicated fpu - avoid if possible).

Binary Numbers, signed vs unsigned

On the msp430, a word is 16 bits. So a C 'int' is 16 bits.
16 bits can hold 65536 different values:

An unsigned int represents values between 0 -> 65536

Binary numbers are usually represented using the “two's complement:” representation
A signed integer represents values between -32768 -> 32767

For a 3 bit number:

	Unsigned	signed
000	0	0
001	1	1
010	2	2
011	3	3
100	4	-4
101	5	-3
110	6	-2
111	7	-1

To get the value of a negative number you ignore the most significant bit as sign, flip (inverse all the other bits and add 1.

Why? Addition and subtraction work very nicely: eg take $2 - 3$. We know $2 - 3$ should be -1.
To accomplish $2-3$, take $2 + (-3)$, ie $010 + 101 = 111 = -1$.

Binary Numbers, signed vs unsigned

If you are interpreting a number as a signed value: a 1 in the MSB indicates a negative value.
To multiply a number by -1:

- a) Invert all the bits
- b) add 1 to the result:

Eg: $3 = 011 \rightarrow 100 + 1 = 101 = -3$

To go back: $101 \rightarrow 010 + 1 = 011 = 3$

When writing the hexadecimal value of a variable, you almost never see negatives.

ie: (char) -1 would often be expressed as: 0xFF

Indentation.

Please use proper indentation of your C code to make it readable! Tabs of 3-4 spaces are generally best.

There are tools that can help. Many text editors can help you indent properly.

For Mac: install “indent” using macports.

See <http://www.cprogramming.com/tutorial/style.html>

for more details than you care about, see: http://en.wikipedia.org/wiki/Indent_style

Activity 3 Due on canvas before lecture on Feb. 25th

Find the values of x after each of the following C commands (run on an MSP430). Answer in hexadecimal.

unsigned int x = 6;

a) x %= 4;

b) x = 96 >> 2;

c) x = ~65280; Hint: 65280 = 0xFF00

d) x = 32769 << 4; Hint: 32769 = 0x8001

2) Write the lines of C code needed to:

a) set P1.0 to P1.3 to be outputs and P1.4 to P1.7 to be inputs

b) starts a for loop that continuously copies the values on the inputs to the values of the outputs (ie P1.4 -> P1.0, P1.5 -> P1.1 etc).

c) if all four of the inputs are 0, exit the loop.

Mixing C and Assembly code:

in a C program you can:

```
asm("assembler text");
```

For gcc, see: <https://gcc.gnu.org/onlinedocs/gcc/Extended-Asm.html>

This can be useful for sections of code that need to be as fast as possible!

But must be done with care to make sure that you that you don't violate the compiler's assumptions about registers used!

Some Resources for C programming:

Operators

[http://en.wikipedia.org/wiki/Operators in C and C%2B%2B#Table](http://en.wikipedia.org/wiki/Operators_in_C_and_C%2B%2B#Table)

Operator Precedence:

[http://en.wikipedia.org/wiki/Operators in C and C%2B%2B#Operator precedence](http://en.wikipedia.org/wiki/Operators_in_C_and_C%2B%2B#Operator_precedence)

C Library reference guide:

http://www.acm.uiuc.edu/webmonkeys/book/c_guide/

Textbook: Introduction to Embedded Systems Using Microcontrollers and the MSP430

<http://webcat2.library.ubc.ca/vwebv/holdingsInfo?bibId=7372090>

Some MSP430 examples:

http://dbindner.freeshell.org/msp430/#_increasing_the_clock_speed

Using peripherals

```
#include "msp430.h"
```

```
void main(void)
```

```
{
```

```
    WDTCTL = WDTPW + WDTHOLD;
```

```
    // Stop WDT
```

```
    ADC10CTL0 = ADC10SHT_2 + ADC10ON;
```

```
    // ADC10ON
```

```
    ADC10CTL1 = INCH_1;
```

```
    // input A1
```

```
    ADC10AE0 |= 0x02;
```

```
    // PA.1 ADC option select
```

```
    P1DIR |= 0x01 ;
```

```
    // Set P1.0 to output direction
```

```
    for (;;) 
```

```
    {
```

```
        ADC10CTL0 |= ENC + ADC10SC;
```

```
        // Sampling and conversion start
```

```
        while (ADC10CTL1 & ADC10BUSY);
```

```
        // ADC10BUSY?
```

```
        if (ADC10MEM < 0x2FF)
```

```
            P1OUT &= ~0x01;
```

```
            // Clear P1.0 LED off
```

```
        else
```

```
            P1OUT |= 0x01;
```

```
            // Set P1.0 LED on
```

```
        unsigned i;
```

```
        for (i = 0xFFFF; i > 0; i--);
```

```
        // Delay
```

```
    }
```

```
}
```

READING THE DATASHEET IS ESSENTIAL!
for this, Chapter 22 - ADC10

Using peripherals

```
#include "msp430.h"
```

```
void main(void)
```

```
{
```

```
WDTCTL = WDTPW + WDTHOLD;
```

```
// Stop WDT
```

```
ADC10CTL0 = ADC10SHT_2 + ADC10ON;
```

```
// ADC10ON
```

```
ADC10CTL1 = INCH_1;
```

```
// input A1
```

```
ADC10AE0 |= 0x02;
```

```
// PA.1 ADC option select
```

```
P1DIR |= 0x01 ;
```

```
// Set P1.0 to output
```

```
for (;;) 
```

```
{
```

```
ADC10CTL0 |= ENC + ADC10SC;
```

```
// Sampling and conversion start
```

```
while (ADC10CTL1 & ADC10BUSY);
```

```
// ADC10BUSY?
```

```
if (ADC10MEM < 0x2FF)
```

```
    P1OUT &= ~0x01;
```

```
// Clear P1.0 LED off
```

```
else
```

```
    P1OUT |= 0x01;
```

```
// Set P1.0 LED on
```

```
unsigned i;
```

```
for (i = 0xFFFF; i > 0; i--);
```

```
// Delay
```

```
}
```

```
}
```

ADC10CTL0 = ADC10SHT_2 + ADC10ON;

// ADC10ON

22.3.1 ADC10CTL0, ADC10 Control Register 0

15	14	13	12	11	10	9	8
SREFx			ADC10SHTx		ADC10SR	REFOUT	REFBURST
rw-(0)		rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)
7	6	5	4	3	2	1	0
MSC	REF2_5V	REFON	ADC10ON	ADC10IE	ADC10IFG	ENC	ADC10SC
rw-(0)		rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)

Can be modified only when ENC = 0

SREFx	Bits 15-13	Select reference. 000 $V_{Rn} = V_{CC}$ and $V_{Rl} = V_{SS}$ 001 $V_{Rn} = V_{REF+}$ and $V_{Rl} = V_{SS}$ 010 $V_{Rn} = V_{REF+}$ and $V_{Rl} = V_{SS}$. Devices with V_{REF+} only. 011 $V_{Rn} =$ Buffered V_{REF+} and $V_{Rl} = V_{SS}$. Devices with V_{REF+} pin only. 100 $V_{Rn} = V_{CC}$ and $V_{Rl} = V_{REF-}/V_{REF+}$. Devices with V_{REF-} pin only. 101 $V_{Rn} = V_{REF+}$ and $V_{Rl} = V_{REF-}/V_{REF+}$. Devices with V_{REF+} pins only. 110 $V_{Rn} = V_{REF+}$ and $V_{Rl} = V_{REF-}/V_{REF+}$. Devices with V_{REF+} pins only. 111 $V_{Rn} =$ Buffered V_{REF+} and $V_{Rl} = V_{REF-}/V_{REF+}$. Devices with V_{REF+} pins only.
ADC10SHTx	Bits 12-11	ADC10 sample-and-hold time 00 4 × ADC10CLKs 01 8 × ADC10CLKs 10 16 × ADC10CLKs 11 64 × ADC10CLKs
ADC10SR	Bit 10	ADC10 sampling rate. This bit selects the reference buffer drive capability for the maximum sampling rate. Setting ADC10SR reduces the current consumption of the reference buffer. 0 Reference buffer supports up to ~200 ksp/s 1 Reference buffer supports up to ~50 ksp/s
REFOUT	Bit 9	Reference output 0 Reference output off 1 Reference output on. Devices with V_{REF+}/V_{REF-} pin only.
REFBURST	Bit 8	Reference burst. 0 Reference buffer on continuously 1 Reference buffer on only during sample-and-conversion
MSC	Bit 7	Multiple sample and conversion. Valid only for sequence or repeated modes. 0 The sampling requires a rising edge of the SHI signal to trigger each sample-and-conversion. 1 The first rising edge of the SHI signal triggers the sampling timer, but further sample-and-conversions are performed automatically as soon as the prior conversion is completed
REF2_5V	Bit 6	Reference-generator voltage. REFON must also be set. 0 1.5 V 1 2.5 V
REFON	Bit 5	Reference generator on 0 Reference off 1 Reference on
ADC10ON	Bit 4	ADC10 on 0 ADC10 off 1 ADC10 on
ADC10IE	Bit 3	ADC10 interrupt enable 0 Interrupt disabled 1 Interrupt enabled

ADC10 Registers

ADC10IFG	Bit 2	ADC10 interrupt flag. This bit is set if ADC10MEM is loaded with a conversion result. It is automatically reset when the interrupt request is accepted, or it may be reset by software. When using the DTC this flag is set when a block of transfers is completed. 0 No interrupt pending 1 Interrupt pending
ENC	Bit 1	Enable conversion 0 ADC10 disabled 1 ADC10 enabled
ADC10SC	Bit 0	Start conversion. Software-controlled sample-and-conversion start. ADC10SC and ENC may be set together with one instruction. ADC10SC is reset automatically. 0 No sample-and-conversion start 1 Start sample-and-conversion

ADC10CTL0 = ADC10SHT_2 + ADC10ON;

// ADC10ON

22.3.1 ADC10CTL0, ADC10 Control Register 0

15	14	13	12	11	10	9	8
SREFx		ADC10SHTx			ADC10SR	REFOUT	REFBURST
rw-(0)		rw-(0)			rw-(0)	rw-(0)	rw-(0)
7	6	5	4	3	2	1	0
MSC	REF2_5V	REFON	ADC10ON	ADC10IE	ADC10IFG	ENC	ADC10SC
Can be modified only when ENC = 0							

SREFx	Bits 15-13	Select reference. 000 $V_{R1} = V_{CC}$ and $V_{R2} = V_{SS}$ 001 $V_{R1} = V_{REF+}$ and $V_{R2} = V_{SS}$ 010 $V_{R1} = V_{REF+}$ and $V_{R2} = V_{SS}$. Devices with V_{REF+} pin only. 011 $V_{R1} =$ Buffered V_{REF+} and $V_{R2} = V_{SS}$. Devices with V_{REF+} pin only. 100 $V_{R1} = V_{CC}$ and $V_{R2} = V_{REF-}/V_{REF+}$. Devices with V_{REF-} pin only. 101 $V_{R1} = V_{REF+}$ and $V_{R2} = V_{REF-}/V_{REF+}$. Devices with V_{REF-} pins only. 110 $V_{R1} = V_{REF+}$ and $V_{R2} = V_{REF-}/V_{REF+}$. Devices with V_{REF-} pins only. 111 $V_{R1} =$ Buffered V_{REF+} and $V_{R2} = V_{REF-}/V_{REF+}$. Devices with V_{REF-} pins only.
ADC10SHTx	Bits 12-11	ADC10 sample-and-hold time 00 $4 \times$ ADC10CLKs 01 $8 \times$ ADC10CLKs 10 $16 \times$ ADC10CLKs 11 $32 \times$ ADC10CLKs
ADC10SR	Bit 10	ADC10 sampling rate. This bit selects the reference buffer drive capability for the maximum sampling rate. Setting ADC10SR reduces the current consumption of the reference buffer. 0 Reference buffer supports up to ~ 200 ksp/s 1 Reference buffer supports up to ~ 50 ksp/s
REFOUT	Bit 9	Reference output 0 Reference output off 1 Reference output on. Devices with V_{REF-}/V_{REF+} pin only.
REFBURST	Bit 8	Reference burst. 0 Reference buffer on continuously 1 Reference buffer on only during sample-and-conversion
MSC	Bit 7	Multiple sample and conversion. Valid only for sequence or repeated modes. 0 The sampling requires a rising edge of the SHI signal to trigger each sample-and-conversion. 1 The first rising edge of the SHI signal triggers the sampling timer, but further sample-and-conversions are performed automatically as soon as the prior conversion is completed
REF2_5V	Bit 6	Reference-generator voltage. REFON must also be set. 0 1.5 V 1 2.5 V
REFON	Bit 5	Reference generator on 0 Reference off 1 Reference on
ADC10ON	Bit 4	ADC10 on 0 ADC10 off 1 ADC10 on
ADC10IE	Bit 3	ADC10 interrupt enable 0 Interrupt disabled 1 Interrupt enabled

If the register descriptions don't have enough information then:

- 1) Look back earlier in the ADC10 chapter for more description of the operation.
- 2) Check the text book for an alternative description.
- 3) Ask a classmate or one of us!

ADC10IFG	Bit 2	ADC10 interrupt flag. This bit is set if ADC10MEM is loaded with a conversion result. It is automatically reset when the interrupt request is accepted, or it may be reset by software. When using the DTC this flag is set when a block of transfers is completed. 0 No interrupt pending 1 Interrupt pending
ENC	Bit 1	Enable conversion 0 ADC10 disabled 1 ADC10 enabled
ADC10SC	Bit 0	Start conversion. Software-controlled sample-and-conversion start. ADC10SC and ENC may be set together with one instruction. ADC10SC is reset automatically. 0 No sample-and-conversion start 1 Start sample-and-conversion

Using peripherals

```
#include "msp430.h"
```

```
void main(void)
```

```
{
```

```
    WDTCTL = WDTPW + WDTCTL; // Stop WDT
```

```
    ADC10CTL0 = ADC10SHT_2 + ADC10ON; // ADC10ON
```

```
    ADC10CTL1 = INCH_1; // input A1 (P1.1)
```

```
    ADC10AE0 |= 0x02; // PA.1 ADC option select
```

```
    P1DIR |= 0x01; // Set P1.0 to output direction
```

```
    for (;;) // Infinite loop
```

```
    {
```

```
        ADC10CTL0 |= ENC + ADC10SC; // Sampling and conversion start
```

```
        while (ADC10CTL1 & ADC10BUSY); // ADC10BUSY?
```

```
        if (ADC10MEM < 0x2FF)
```

```
            P1OUT &= ~0x01; // Clear P1.0 LED off
```

```
        else
```

```
            P1OUT |= 0x01; // Set P1.0 LED on
```

```
        unsigned i;
```

```
        for (i = 0xFFFF; i > 0; i--); // Delay
```

```
    }
```

```
}
```

ADC10CTL1 = INCH_1;

// input A1



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ADC10 Registers

22.3.2 ADC10CTL1, ADC10 Control Register 1

15	14	13	12	11	10	9	8
INCHx				SHSx	ADC10DF	ISSH	
rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)
7	6	5	4	3	2	1	0
ADC10DIVx		ADC10SSELx		CONSEQx		ADC10BUSY	
rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	r-0

Can be modified only when ENC = 0

INCHx	Bits 15-12	Input channel select. These bits select the channel for a single-conversion or the highest channel for a sequence of conversions. Only available ADC channels should be selected. See device specific datasheet.
		0000 A0
		0001 A1
		0010 A2
		0011 A3
		0100 A4
		0101 A5
		0110 A6
		0111 A7
		1000 V_{REF+}
		1001 V_{REF+}/V_{REF-}
		1010 Temperature sensor
		1011 $(V_{CC} - V_{SS}) / 2$
		1100 $(V_{CC} - V_{SS}) / 2$, A12 on MSP430F22xx devices
		1101 $(V_{CC} - V_{SS}) / 2$, A13 on MSP430F22xx devices
		1110 $(V_{CC} - V_{SS}) / 2$, A14 on MSP430F22xx devices
		1111 $(V_{CC} - V_{SS}) / 2$, A15 on MSP430F22xx devices
		00 ADC10SC bit
		01 Timer_A.OUT1 ⁽¹⁾
		10 Timer_A.OUT0 ⁽¹⁾
		11 Timer_A.OUT2 (Timer_A.OUT1 on MSP430F20x0, MSP430G2x31, and MSP430G2x30 devices) ⁽¹⁾
ADC10DF	Bit 9	ADC10 data format
		0 Straight binary
		1 2s complement
ISSH	Bit 8	Invert signal sample-and-hold
		0 The sample-input signal is not inverted.
		1 The sample-input signal is inverted.
ADC10DIVx	Bits 7-5	ADC10 clock divider
		000 /1
		001 /2
		010 /3
		011 /4
		100 /5
		101 /6
		110 /7
		111 /8
ADC10SSELx	Bits 4-3	ADC10 clock source select
		00 ADC10OSC
		01 ACLK
		10 MCLK
		11 SMCLK

⁽¹⁾ Timer triggers are from Timer0_Ax if more than one timer module exists on the device.

ADC10 Registers

CONSEQx	Bits 2-1	Conversion sequence mode select
		00 Single-channel-single-conversion
		01 Sequence-of-channels
		10 Repeat-single-channel
		11 Repeat-sequence-of-channels
ADC10BUSY	Bit 0	ADC10 busy. This bit indicates an active sample or conversion operation
		0 No operation is active.
		1 A sequence, sample, or conversion is active.

ADC10CTL1 = INCH_1;

// input A1



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ADC10 Registers

22.3.2 ADC10CTL1, ADC10 Control Register 1

15	14	13	12	11	10	9	8
INCHx				SHSx	ADC10DF	ISSH	
rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)
7	6	5	4	3	2	1	0
ADC10DIVx		ADC10SSELx		CONSEQx		ADC10BUSY	
rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	r-0

Can be modified only when ENC = 0

INCHx	Bits 15-12	Input channel select. These bits select the channel for a single-conversion or the highest channel for a sequence of conversions. Only available ADC channels should be selected. See device specific datasheet.
	0000	A0
	0001	A1
	0010	A2
	0011	A3
	0100	A4
	0101	A5
	0110	A6
	0111	A7
	1000	V _{REF+}
	1001	V _{REF-} /V _{REFP}
	1010	Temperature sensor
	1011	(V _{CC} - V _{SS}) / 2
	1100	(V _{CC} - V _{SS}) / 2, A12 on MSP430F22xx devices
	1101	(V _{CC} - V _{SS}) / 2, A13 on MSP430F22xx devices
	1110	(V _{CC} - V _{SS}) / 2, A14 on MSP430F22xx devices
	1111	(V _{CC} - V _{SS}) / 2, A15 on MSP430F22xx devices
	00	ADC10SC bit
	01	Timer_A.OUT1 ⁽¹⁾
	10	Timer_A.OUT0 ⁽¹⁾
	11	Timer_A.OUT2 (Timer_A.OUT1 on MSP430F20x0, MSP430G2x31, and MSP430G2x30 devices) ⁽¹⁾
ADC10DF	Bit 9	ADC10 data format
	0	Straight binary
	1	2s complement
ISSH	Bit 8	Invert signal sample-and-hold
	0	The sample-input signal is not inverted.
	1	The sample-input signal is inverted.
ADC10DIVx	Bits 7-5	ADC10 clock divider
	000	/1
	001	/2
	010	/3
	011	/4
	100	/5
	101	/6
	110	/7
	111	/8
ADC10SSELx	Bits 4-3	ADC10 clock source select
	00	ADC10OSC
	01	ACLK
	10	MCLK
	11	SMCLK

⁽¹⁾ Timer triggers are from Timer0_Ax if more than one timer module exists on the device.

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Table 2. Terminal Functions

NAME	NO.		I/O	DESCRIPTION
	14 N, PW	16 RSA		
P1.0/ TA0CLK/ ACLK/ A0	2	1	I/O	General-purpose digital I/O pin Timer0_A, clock signal TACLK input ACLK signal output ADC10 analog input A0 ⁽¹⁾
P1.1/ TA0.0/ A1	3	2	I/O	General-purpose digital I/O pin Timer0_A, capture: CC10A input, compare: Out0 output ADC10 analog input A1 ⁽¹⁾
P1.2/ TA0.1/ A2	4	3	I/O	General-purpose digital I/O pin Timer0_A, capture: CC11A input, compare: Out1 output ADC10 analog input A2 ⁽¹⁾
P1.3/ ADC10CLK/ A3/ VREF-/VEREF	5	4	I/O	General-purpose digital I/O pin ADC10, conversion clock output ⁽¹⁾ ADC10 analog input A3 ⁽¹⁾ ADC10 negative reference voltage ⁽¹⁾
P1.4/ SMCLK/ A4/ VREF+/VEREF+/ TCK	6	5	I/O	General-purpose digital I/O pin SMCLK signal output ADC10 analog input A4 ⁽¹⁾ ADC10 positive reference voltage ⁽¹⁾ JTAG test clock, input terminal for device programming
P1.5/ TA0.0/ A5/ SCLK/ TMS	7	6	I/O	General-purpose digital I/O pin Timer0_A, compare: Out0 output ADC10 analog input A5 ⁽¹⁾ USI: clock input in I2C mode; clock input/output in SPI mode JTAG test mode select, input terminal for device programming
P1.6/ TA0.1/ A6/ SDO/ SCL/ TDI/TCLK	8	7	I/O	General-purpose digital I/O pin Timer0_A, capture: CC11A input, compare: Out1 output ADC10 analog input A6 ⁽¹⁾ USI: Data output in SPI mode USI: I2C clock in I2C mode JTAG test data input or test clock input during programming
P1.7/ A7/ SDI/ SDA/ TDO/TDI ⁽²⁾	9	8	I/O	General-purpose digital I/O pin ADC10 analog input A7 ⁽¹⁾ USI: Data input in SPI mode USI: I2C data in I2C mode JTAG test data output terminal or test data input during programming

ADC10 Registers

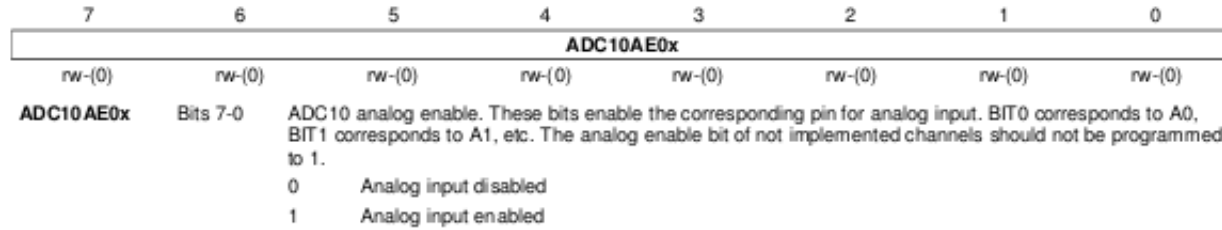
CONSEQx	Bits 2-1	Conversion sequence mode select
	00	Single-channel-single-conversion
	01	Sequence-of-channels
	10	Repeat-single-channel
	11	Repeat-sequence-of-channels
ADC10BUSY	Bit 0	ADC10 busy. This bit indicates an active sample or conversion operation
	0	No operation is active.
	1	A sequence, sample, or conversion is active.

DVSS	14	13, 14	NA	Ground reference
------	----	--------	----	------------------

```
ADC10AE0 |= 0x02;
```

```
// PA.1 ADC option select
```

22.3.3 ADC10AE0, Analog (Input) Enable Control Register 0



Using peripherals

```
#include "msp430.h"
```

```
void main(void)
```

```
{
```

```
    WDTCTL = WDTPW + WDTHOLD;
```

```
    // Stop WDT
```

```
    ADC10CTL0 = ADC10SHT_2 + ADC10ON;
```

```
    // ADC10ON
```

```
    ADC10CTL1 = INCH_1;
```

```
    // input A1
```

```
    ADC10AE0 |= 0x02;
```

```
    // PA.1 ADC option select
```

```
    P1DIR |= 0x01 ;
```

```
    // Set P1.0 to output direction
```

```
    for (;;)
    {
```

```
        ADC10CTL0 |= ENC + ADC10SC;
```

```
        // Sampling and conversion start
```

```
        while (ADC10CTL1 & ADC10BUSY);
```

```
        // ADC10BUSY?
```

```
        if (ADC10MEM < 0x2FF)
```

```
            P1OUT &= ~0x01;
```

```
        // Clear P1.0 LED off
```

```
        else
```

```
            P1OUT |= 0x01;
```

```
        // Set P1.0 LED on
```

```
        unsigned i;
```

```
        for (i = 0xFFFF; i > 0; i--);
```

```
        // Delay
```

```
    }
```

```
}
```

ADC10CTL0 = ADC10SHT_2 + ADC10ON;

// ADC10ON

22.3.1 ADC10CTL0, ADC10 Control Register 0

15	14	13	12	11	10	9	8
SREFx		ADC10SHTx			ADC10SR	REFOUT	REFBURST
rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)
7	6	5	4	3	2	1	0
MSC	REF2_5V	REFON	ADC10ON	ADC10IE	ADC10IFG	ENC	ADC10SC
rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)

Can be modified only when ENC = 0

SREFx	Bits 15-13	Select reference. 000 $V_{Rn} = V_{CC}$ and $V_{Rn} = V_{SS}$ 001 $V_{Rn} = V_{REF+}$ and $V_{Rn} = V_{SS}$ 010 $V_{Rn} = V_{REF+}$ and $V_{Rn} = V_{SS}$. Devices with V_{REF+} only. 011 $V_{Rn} = \text{Buffered } V_{REF+}$ and $V_{Rn} = V_{SS}$. Devices with V_{REF+} pin only. 100 $V_{Rn} = V_{CC}$ and $V_{Rn} = V_{REF-} / V_{REF+}$. Devices with V_{REF-} pin only. 101 $V_{Rn} = V_{REF+}$ and $V_{Rn} = V_{REF-} / V_{REF+}$. Devices with $V_{REF+/-}$ pins only. 110 $V_{Rn} = V_{REF+}$ and $V_{Rn} = V_{REF-} / V_{REF+}$. Devices with $V_{REF+/-}$ pins only. 111 $V_{Rn} = \text{Buffered } V_{REF+}$ and $V_{Rn} = V_{REF-} / V_{REF+}$. Devices with $V_{REF+/-}$ pins only.
ADC10SHTx	Bits 12-11	ADC10 sample-and-hold time 00 4 × ADC10CLKs 01 8 × ADC10CLKs 10 16 × ADC10CLKs 11 64 × ADC10CLKs
ADC10SR	Bit 10	ADC10 sampling rate. This bit selects the reference buffer drive capability for the maximum sampling rate. Setting ADC10SR reduces the current consumption of the reference buffer. 0 Reference buffer supports up to ~200 kbps 1 Reference buffer supports up to ~50 kbps
REFOUT	Bit 9	Reference output 0 Reference output off 1 Reference output on. Devices with V_{REF+} / V_{REF-} pin only.
REFBURST	Bit 8	Reference burst. 0 Reference buffer on continuously 1 Reference buffer on only during sample-and-conversion
MSC	Bit 7	Multiple sample and conversion. Valid only for sequence or repeated modes. 0 The sampling requires a rising edge of the SHI signal to trigger each sample-and-conversion. 1 The first rising edge of the SHI signal triggers the sampling timer, but further sample-and-conversions are performed automatically as soon as the prior conversion is completed
REF2_5V	Bit 6	Reference-generator voltage. REFON must also be set. 0 1.5 V 1 2.5 V
REFON	Bit 5	Reference generator on 0 Reference off 1 Reference on
ADC10ON	Bit 4	ADC10 on 0 ADC10 off 1 ADC10 on
ADC10IE	Bit 3	ADC10 interrupt enable 0 Interrupt disabled 1 Interrupt enabled

If the register descriptions don't have enough information then:

- 1) Look back earlier in the ADC10 chapter for more description of the operation.
- 2) Check the text book for an alternative
- 3) Ask a classmate or one of us!

ADC10IFG	Bit 2	ADC10 interrupt flag. This bit is set if ADC10MEM is loaded with a conversion result. It is automatically reset when the interrupt request is accepted, or it may be reset by software. When using the DTC this flag is set when a block of transfers is completed. 0 No interrupt pending 1 Interrupt pending
ENC	Bit 1	Enable conversion 0 ADC10 disabled 1 ADC10 enabled
ADC10SC	Bit 0	Start conversion. Software-controlled sample-and-conversion start. ADC10SC and ENC may be set together with one instruction. ADC10SC is reset automatically. 0 No sample-and-conversion start 1 Start sample-and-conversion

Lab 3/4, ADC:

```
ADC10CTL0 |= ENC + ADC10SC;  
while (ADC10CTL1 & ADC10BUSY);
```

```
while (a & b){
```

```
}
```

vs

```
while(a & b);
```

```
{
```

```
}
```