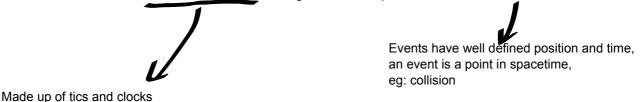
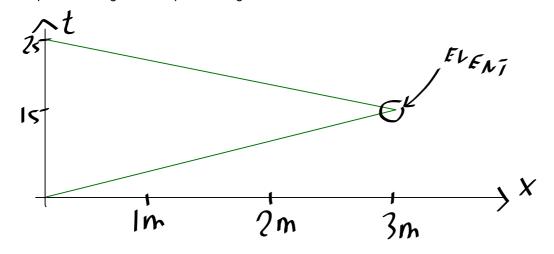


Start with an example: playing ping-pong on a moving airplane is just like playing on the ground, unless there is turbulance or the plane is accelerating or turning or etc...

DEF: A frame of reference is a coordinate system allowing to determine position and time of events



A spacetime diagram example: a rolling ball hits a wall at x=3m and t=1s and bounces back



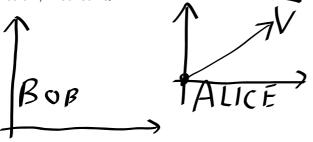
-> Clicker Question

Observers at rest relative to each other use the same frame of reference to make measurements. A frame of reference is not the same as an observer.

DEF: An inertial frame of reference (IRF) is one in which Newton's 1st law of motion holds

Claim: all IRFs move with constant velocity with respect to each other.

Proof: Consider an object at rest w.r.t. frame A. No forces are acting on it, by Newton's first law. If frame A is moving with velocity v w.r.t. frame B, then this object is moving with velocity v in frame B. Since no forces are acting on it, by the above definition of IRF Newton's 1st law, v=const. QED.

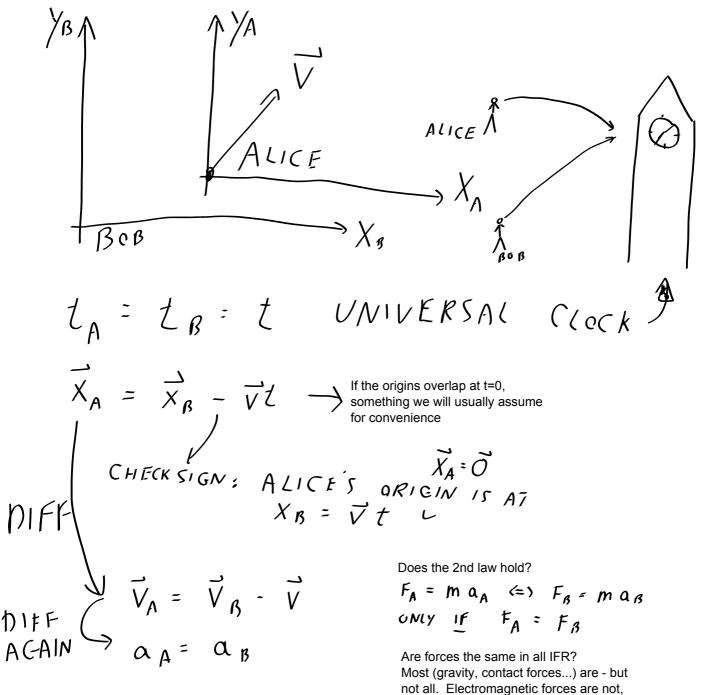


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## Principle of relativity: the laws of physics are the same in all IRFs.

To be able to verify this principle, we need trasformations: ways to compute quantities in one frame if they are known in another.

Eg: Galilean Transformations (familiar from everyday life and highshool/1st year physics)



More to come next lecture.-

as you saw in tutorial 1.