

**Phys529B: Topics of Quantum Theory**

**Lecture 15: identifying Non-Fermi liquids via RGE**

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$$\Lambda_{uv} \quad \phi_0(x) \quad H(g_{01}, g_{02}, \dots; m, \Lambda_{uv})$$

$$\Lambda \quad \phi(x) \quad H(g_1(\Lambda), g_2(\Lambda), \dots; m(\Lambda), \Lambda; z(\Lambda))$$

$$\phi(x) = \sum^{-\frac{1}{2}} \phi_R(x)$$

$$\text{or} = \sum^{\frac{1}{2}} \phi_0(x)$$

$$\Lambda_{2R} \quad \phi_R(x) \quad H(g_{1R}, g_{2R}, \dots; m_R)$$

- Callan-Symanzik approach (also Coleman-Weinberg applications) : Utilizing Green's functions to obtain RGEs and understand scale Transformations
- An interesting application to cold gases can be found in Yang, Jiang and Zhou, PRL 124 (22), 225701, 2020, Tricritical physics in 2D Superfluids.

Approach 1:  $\phi(x) = Z^{\frac{1}{2}}(\Lambda) \phi_R(x)$

$$\langle 0 | T \phi(x_1) \phi(x_2) \dots \phi(x_n) | 0 \rangle = G^{(n)}(x_1, \dots, x_n)$$

$$G^{(n)}(x_1, \dots, x_n) = Z^{n/2}(\Lambda) \underbrace{\langle 0 | T \phi_R(x_1) \dots \phi_R(x_n) | 0 \rangle}_c$$

independent of " $\Lambda$ ".

Computed with  $H(g_1(\Lambda), g_2(\Lambda), \dots, g_n(\Lambda); m(\Lambda), \Lambda)$

$$G^{(n)} = G^{(n)}(\dots; \hat{g}_1, \hat{g}_2, \dots, \hat{g}_n(\Lambda); \hat{m}(\Lambda), t)$$

$$t = \ln \Lambda$$

$$\left\{ \frac{\partial}{\partial t} + \beta(\vec{g}) \frac{\partial}{\partial \vec{g}} \right\} G^{(n)} = \underbrace{\left\{ \frac{n}{2} \frac{\delta Z}{\delta \Lambda} \frac{1}{Z} \right\}}_{\gamma(\vec{g})} G^{(n)}$$

$$\left\{ \frac{\partial}{\partial t} + \beta(\vec{g}) \frac{\partial}{\partial \vec{g}} - \frac{n}{2} \gamma(\vec{g}) \right\} G^{(n)} = 0$$

Note:  $Z(t=0, \vec{g}) = 1$

Approach II :  $\phi(x) = \sum^{-1/2}(\Lambda) \phi_0(x)$

$$\langle 0 | T \phi(x_1) \phi(x_2) \dots \phi(x_n) | 0 \rangle = G^{(n)}(x_1, \dots, x_n)$$

$$G^{(n)}(x_1, \dots, x_n) = \sum^{-n/2}(\Lambda) \underbrace{\langle 0 | T \phi_0(x_1) \dots \phi_0(x_n) | 0 \rangle}_c$$

independent of "Λ".

Computed with  $H(g_1(\Lambda), g_2(\Lambda), \dots, g_n(\Lambda); m(\Lambda), \Lambda)$

$$G^{(n)} = G^{(n)}(\dots; \hat{g}_1, \hat{g}_2, \dots, \hat{g}_n(\Lambda); \hat{m}(\Lambda), t)$$

$$t = \ln \Lambda$$

$$\left\{ \frac{\partial}{\partial t} + \beta(\tilde{g}) \frac{\partial}{\partial \tilde{g}} \right\} G^{(n)} = \underbrace{\left\{ \frac{n}{2} \frac{\delta Z}{\delta \Lambda} \frac{1}{Z} \right\}}_{\gamma(\tilde{g})} G^{(n)}$$

$$\left\{ \frac{\partial}{\partial t} + \beta(\tilde{g}) \frac{\partial}{\partial \tilde{g}} + \frac{\hbar}{2} \gamma(\tilde{g}) \right\} G^{(n)} = 0$$

Note :  $Z(t = \ln \frac{\Lambda_{UV}}{\Lambda_{IR}}, \tilde{g}) = 1$

Relations between Approach I and Approach II

$$\text{App I: } \phi(x) = Z_{\text{I}}^{1/2} \phi_R(x); \quad \text{App II: } \phi(x) = Z_{\text{II}}^{-1/2} \phi_0(x)$$

$$Z_{\text{I}}^{1/2} Z_0^{-1} = Z_{\text{II}}^{-1/2} \quad \text{or}$$

$$\frac{1}{Z_{\text{I}}} \frac{\partial}{\partial t} Z_{\text{I}} = - \frac{1}{Z_{\text{II}}} \frac{\partial}{\partial t} Z_{\text{II}}$$



$$\left\{ \frac{\partial}{\partial t} + \beta(\vec{g}) \frac{\partial}{\partial \vec{g}} \right\} G^{(n)} = \left\{ \frac{n}{2} \underbrace{\frac{\delta Z}{\delta \Lambda}}_{\gamma(\vec{g})} \frac{1}{Z} \right\} G^{(n)}$$

$$\left\{ \frac{\partial}{\partial t} + \beta(\vec{g}) \frac{\partial}{\partial \vec{g}} - \gamma(\vec{g}) \right\} G^{(n)} = 0$$

Note:  $Z(t=0, \vec{g}) = 1$

How to use them?

two-point  $n=2$

$$I: \left\{ \frac{\partial}{\partial t} + \beta(\tilde{g}) \frac{\partial}{\partial \tilde{g}} - \gamma(\tilde{g}) \right\} G(p) = 0, \quad G^{(2)}(p) \sim \frac{Z}{p^2}$$

$$Z(\Lambda = \Lambda_{2R}, \tilde{g}) = 1 \rightarrow \frac{\partial}{\partial \tilde{g}} G^{(2)}(p) = 0$$

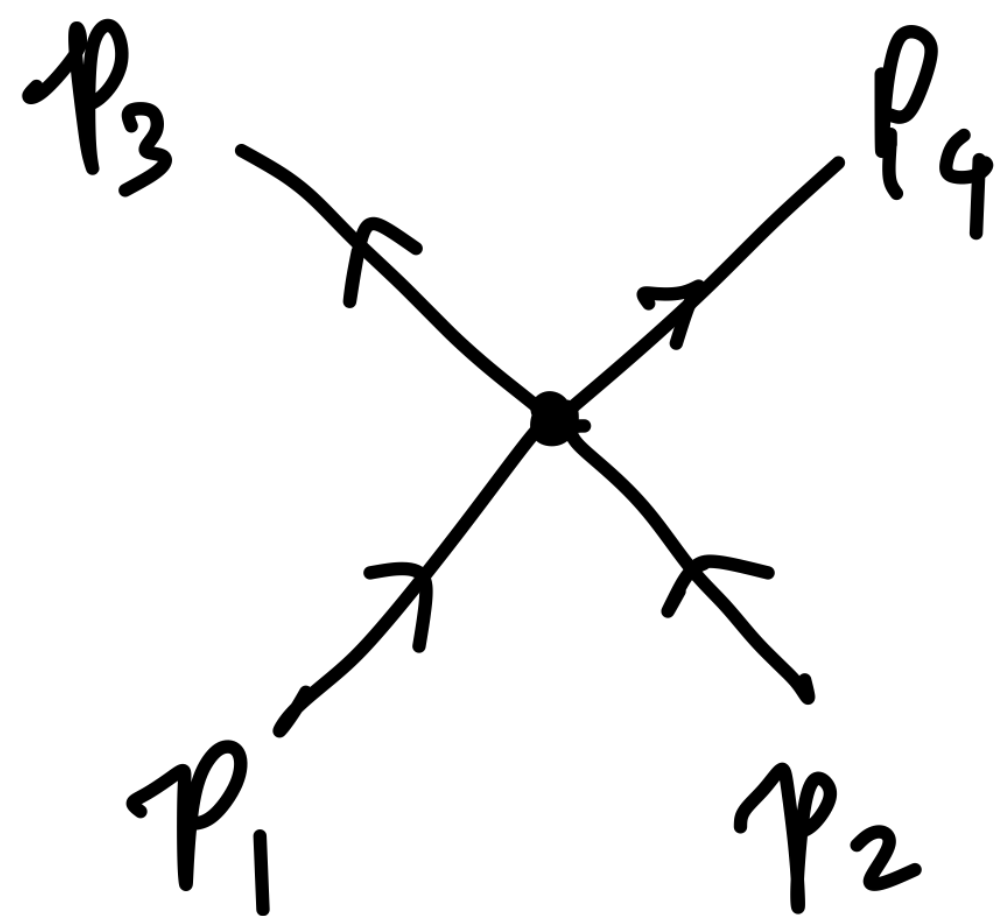
$$\gamma(\tilde{g}) = G(p)^{-1} \frac{\partial}{\partial t} G(p)$$

$\uparrow$   
RGE

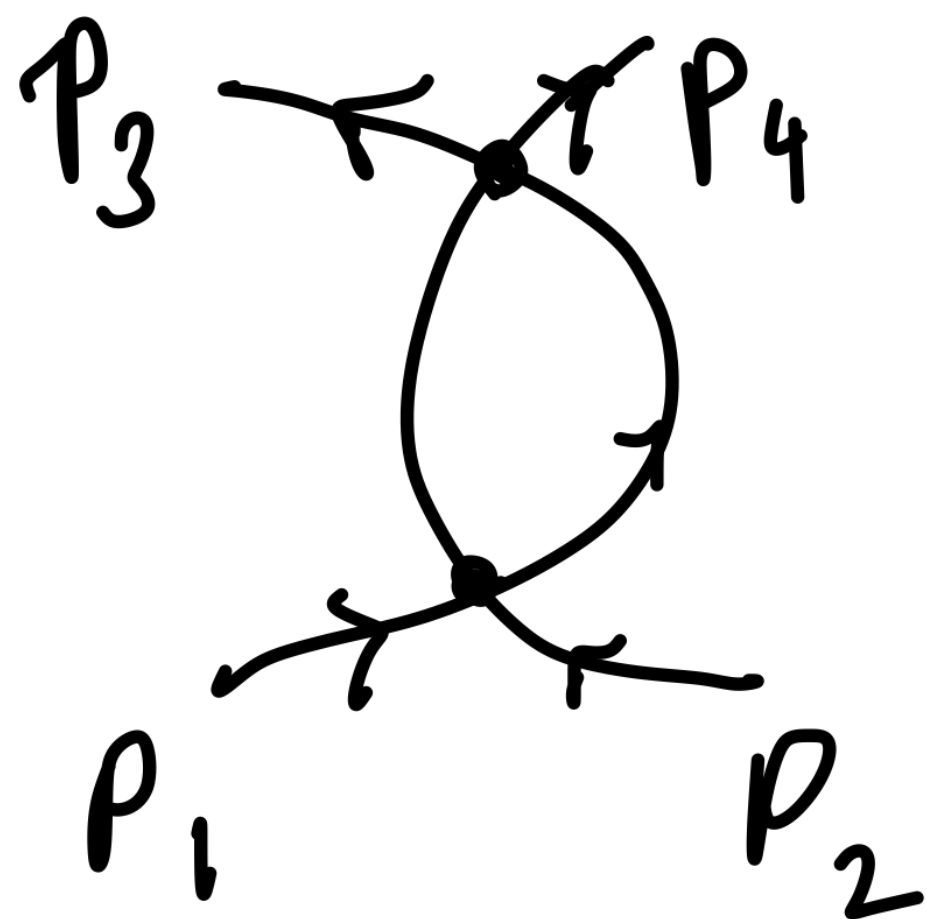
$\uparrow$   
Green-function

$$\text{II: } \left\{ \frac{\partial}{\partial t} + \beta(\tilde{g}) \frac{\partial}{\partial \tilde{g}} - 2\gamma(\tilde{g}) \right\} G(p_1, p_2, p_3, p_4) \doteq 0$$

4-point 1PI



$$\frac{d\tilde{g}}{dt} = \beta(\tilde{g}) = 2\gamma(\tilde{g})\tilde{g} + \tilde{g}(d-1) + \frac{\partial}{\partial t} [X]$$



$$X \doteq \text{1PI} \text{ loop diagram} + \dots$$

↑  
1PI